

Rotational Motion

$$-\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \psi + V \psi = E \psi(r, \theta, \phi) \quad \text{--- (1)}$$

Particle on a ring: r is fixed; $\theta = \pi/2$; $V = 0$

$$-\frac{\hbar^2}{2m} \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \phi^2} = E \psi(\phi) \quad \text{--- (2)}$$

$$\frac{\partial^2 \psi}{\partial \phi^2} = - \frac{2IE}{\hbar^2} \psi(\phi) \quad \text{--- (3)}$$

$\underbrace{\hspace{1.5cm}}_{\substack{\downarrow \\ m_l}}$

$$\frac{\partial^2 \psi}{\partial \phi^2} = - m_l^2 \psi(\phi)$$

$$\psi(\phi) = a_{m_l} e^{i m_l \phi} \quad \text{--- (4)}$$

$$\psi(\phi) = \frac{1}{\sqrt{2\pi}} e^{i m_l \phi} \quad \text{--- (5)}$$

$$m_l = 0, \pm 1, \pm 2, \pm 3 \quad \text{---}$$

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi} \quad \text{--- (6)}$$

Particle on a sphere

r is fixed; $V=0$

⇓

RIAD ROTOR problem

$$-\frac{\hbar^2}{2m} \left[\frac{1}{r^2 \sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial}{\partial\theta} + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right] \Psi = E \Psi(\theta, \phi) \dots (1)$$

$$-\frac{\hbar^2}{2mr^2} \left[\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial}{\partial\theta} + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right] \Psi = E \Psi(\theta, \phi) \dots (2)$$

$$\underbrace{\hspace{15em}}_{\Lambda^2}$$

$$-\frac{\hbar^2}{2mr^2} \Lambda^2 \Psi = E \Psi(\theta, \phi) \dots (3)$$

↑

Legendrian

$$\Psi(\theta, \phi) = \Theta(\theta) \underline{\Phi}(\phi)$$

⇓

$$Y(\theta, \phi) = \Theta(\theta) \underline{\Phi}(\phi) \dots (4)$$

$$\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial}{\partial\theta} Y + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} Y = -\frac{2IE}{\hbar^2} Y$$

$$\beta = \frac{2IE}{\hbar^2}$$

... (5)

$$\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial \Theta}{\partial\theta} + \frac{1}{\sin^2\theta} \frac{\partial^2 \Theta}{\partial\phi^2} = -\beta \Theta$$

$$\frac{\bar{\Phi}}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial \Theta}{\partial\theta} + \Theta \frac{1}{\sin^2\theta} \frac{\partial^2 \bar{\Phi}}{\partial\phi^2} = -\beta \Theta \bar{\Phi}$$

... (6)

Divide eqn. (6) thru' out by $\Theta \bar{\Phi}$

and multiply by $\sin^2\theta$

$$\frac{1}{\Theta} \frac{\sin\theta}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial \Theta}{\partial\theta} + \beta \sin^2\theta = - \frac{1}{\bar{\Phi}} \frac{\partial^2 \bar{\Phi}}{\partial\phi^2}$$

~~~~~ (7)

only a function of  $\theta$

~~~~~  
function of ϕ

both sides are equal to a constant $\Rightarrow m_l^2$

$$- \frac{1}{\bar{\Phi}} \frac{\partial^2 \bar{\Phi}}{\partial\phi^2} = m_l^2 \dots (8)$$

$$\frac{1}{\Theta} \frac{\sin\theta}{\sin\theta} \frac{\partial}{\partial\theta} \sin\theta \frac{\partial \Theta}{\partial\theta} + \beta \sin^2\theta = m_l^2 \dots (9)$$